

Topic 5

Introduction to PLC technology in Mechatronics



Question

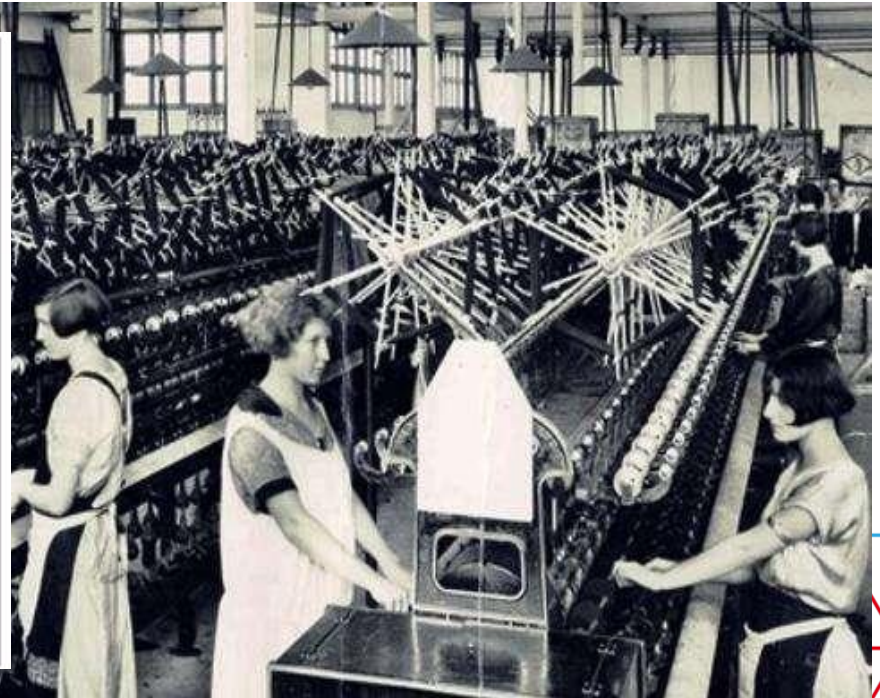
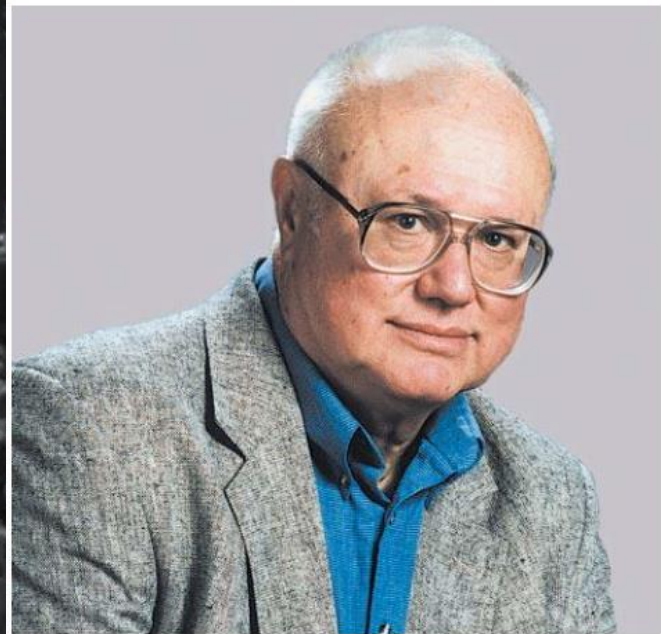


What is PLC



1. History of PLC

The demand for human social development drives the continuous progress of industrial production



1. History of PLC

PLC—— the brain of automated production line



P —— Programmable

L —— Logic

C —— Controller

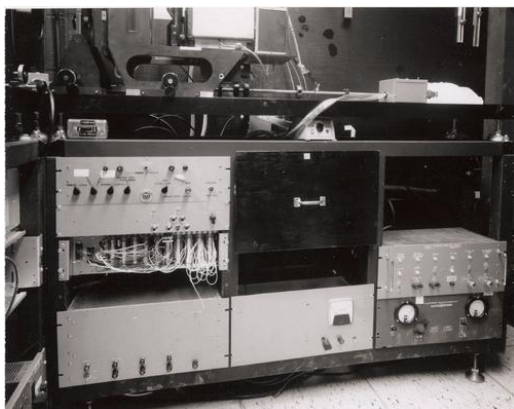
Automated production lines - the result of continuous pursuit of production efficiency



2. Development of PLC

Origin

In the early 1970s



PDP-14 (American DEC)

Practicality

1970s~

In the early 1980s



SC series (Japan Fuji Electric)

rapid growth 1980s~

In the mid-1990s



S5 series (Germany Siemens)

Progress and Improvement

Late 20th century ~ So far



S7 series (Germany Siemens)

3. Brand of PLC

Common PLC brands/manufacturers

SIEMENS
Ingenuity for life



ABB



Rockwell
Automation



OMRON



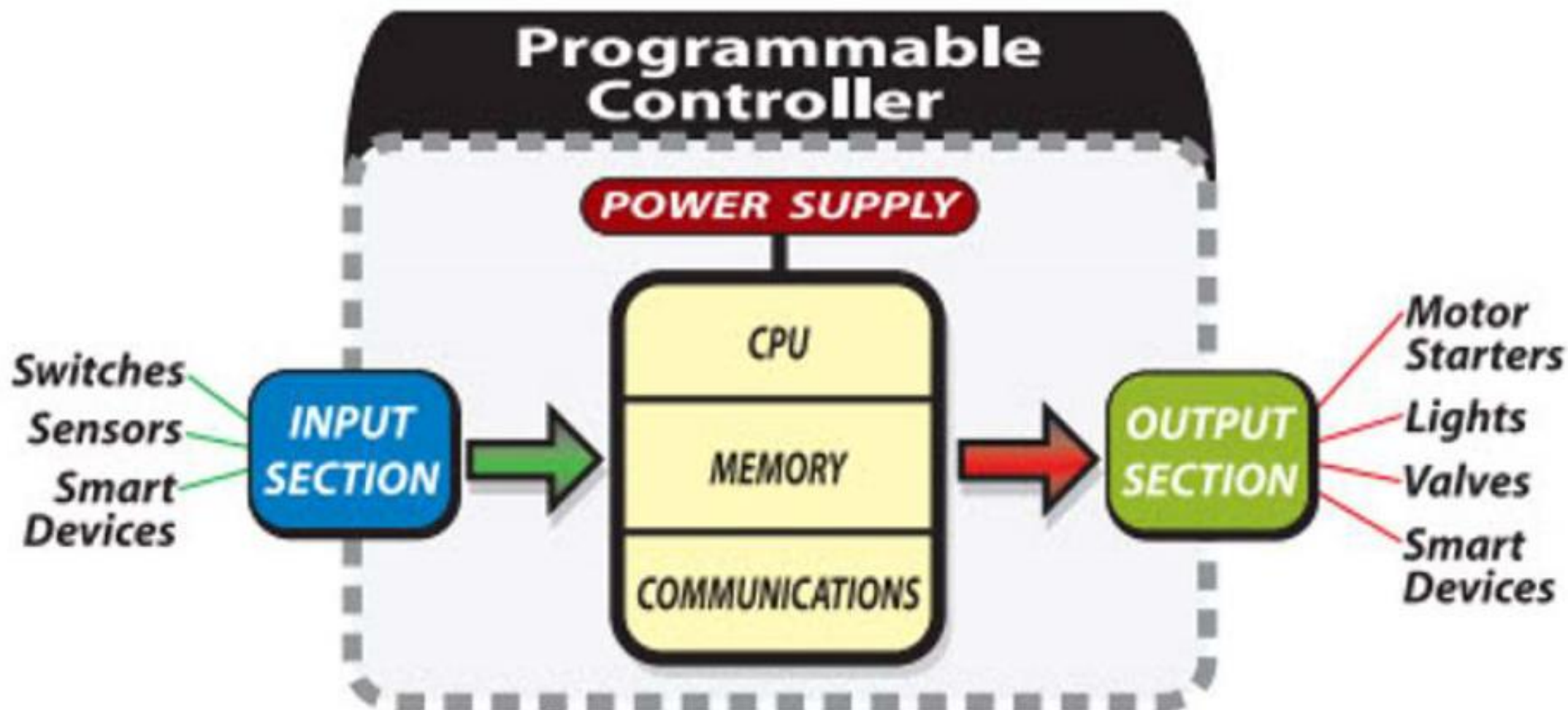
XINJE
信捷

INOVANCE
汇川技术

MITSUBISHI



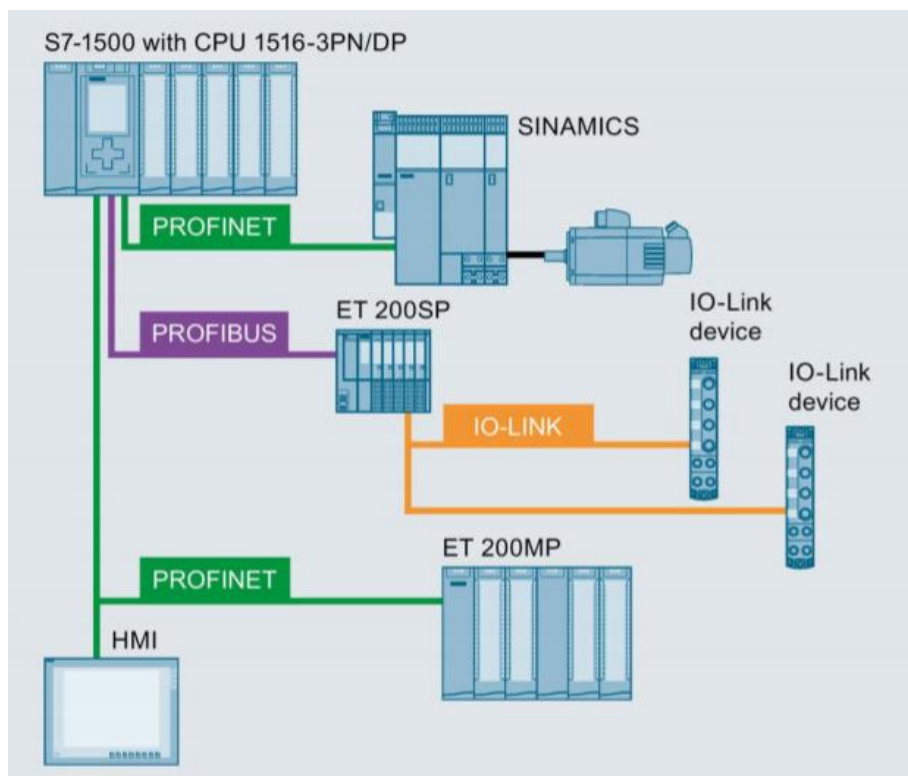
4. Main components of a PLC



Composition of common PLC systems



Composition of common PLC systems



Composition of common PLC systems

1. PLC master station



Power module
PM/PS



S7-1500
CPU



Signal module
DI/DO/AI/AO

Composition of common PLC systems

2. Distributed IO slave station



Distributed IO slave station

=

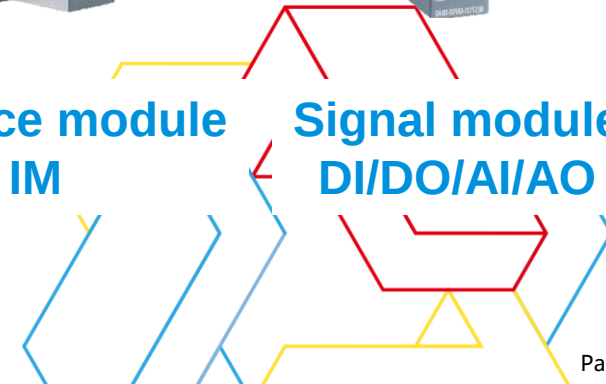


Interface module
IM

+



Signal module
DI/DO/AI/AO



Composition of common PLC systems

3. HMI



Composition of common PLC systems

4. Industrial control software



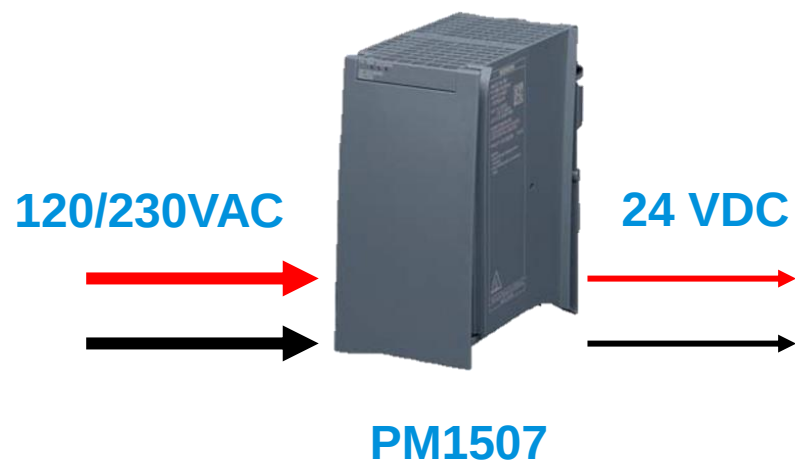
Industrial control software
(TIA/WINCC)



1. PLC master station



1. 1 Power module



1. 2 CPU Module

Siemens' fastest automation controller



The SIMATIC S7-1500 has high-speed backplane bus, PROFINET performance, and extremely short response time. The CPU command processing time can reach 1 ns, achieving extremely high productivity and product quality in the production process.



1. 2 CPU Module

S7-1500 CPU family member

Common series CPU



CPU1511、CPU1512、CPU1513、
CPU1515、CPU1516、CPU1517、
CPU1518

Compact style(C) CPU



CPU1511C、
CPU1512C、
.....

Safety(F) CPU



CPU1513F、
CPU1517F、
.....



1. 2 CPU Module

S7-1500 CPU family member

Motion control (T) CPU



CPU1515T、
CPU1517T、
.....

Redundance(R/H) CPU

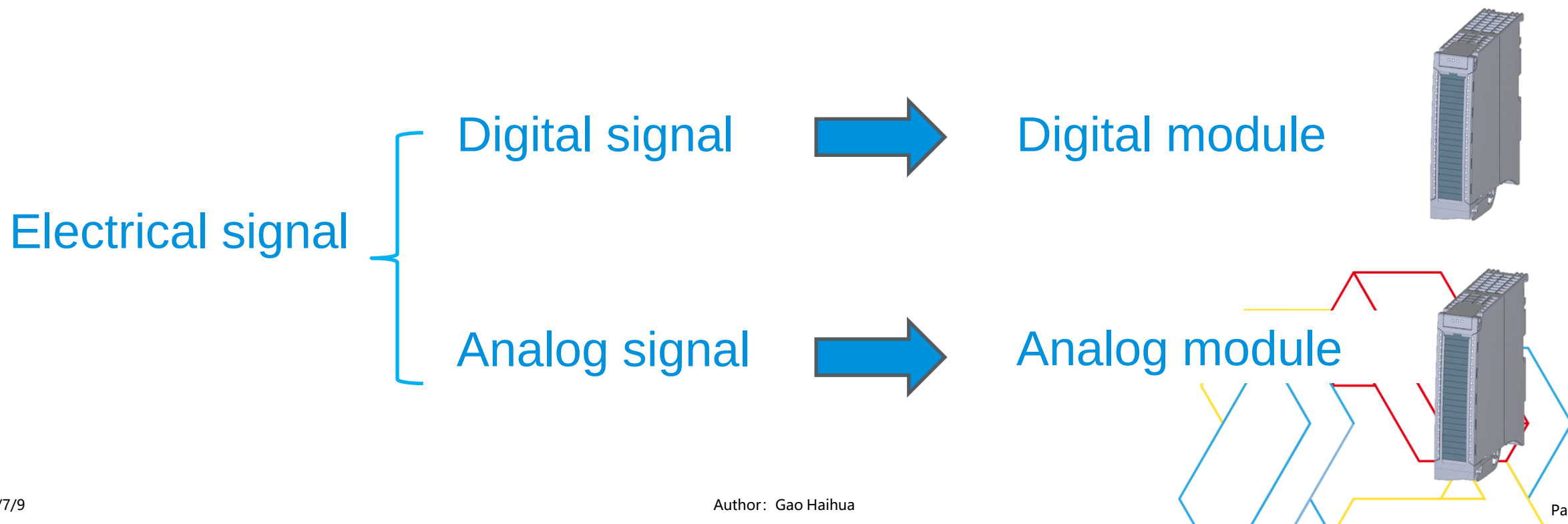


CPU1515R、
CPU1517H、
.....



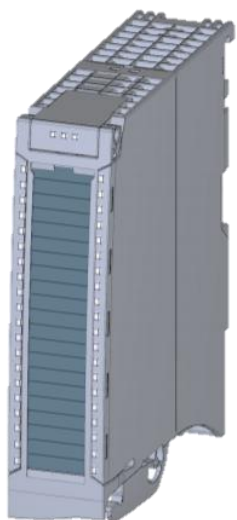
1. 3 Signal Moule

The vast majority of electrical signals used in industrial PLC control systems



1. 3 Signal Moule

Digital Module



DI (Digital Input) module :
Responsible for collecting of on-site input signals
(proximity switches 、 light switches)

DO (Digital Output) module :
Responsible for output signals to executing devices
(solenoid valves, indicator lights, etc.)



1. 3 Signal Moule

wiring



Front connector



Terminal with screw
x 35 mm



Terminal with
clamp x 25 mm

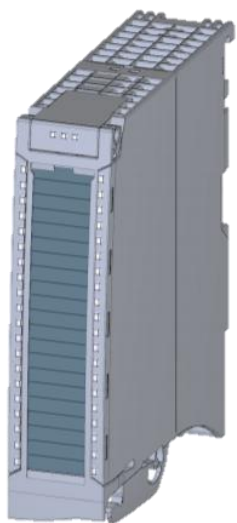


Terminal with
clamp x 35 mm



1. 3 Signal Moule

Analog Module



AI (Analog Input) Module :
Responsible for collecting of on-site input signal
(temperature ,flow)

AO (Analog Output) Module :
Responsible for outputting signals to executing devices
(motors, electromagnetic control valves, etc.)



2. Distributed IO slave station



Interface module
IM



Signal module
DI/DO/AI/AO



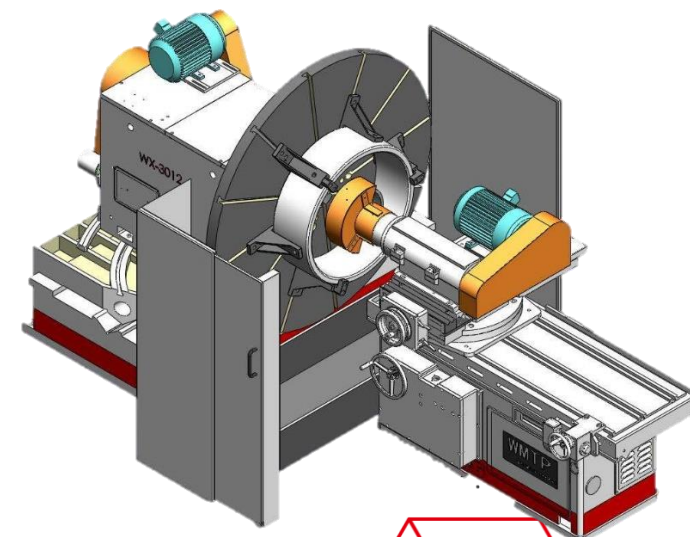
2. Distributed IO salve station



Why do we need ?



Signal cables



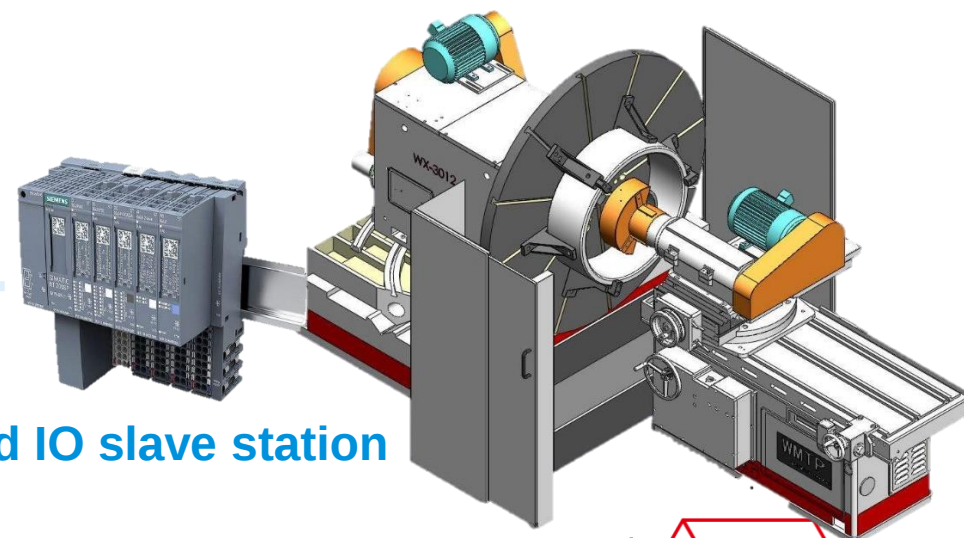
200m



2. Distributed IO slave station

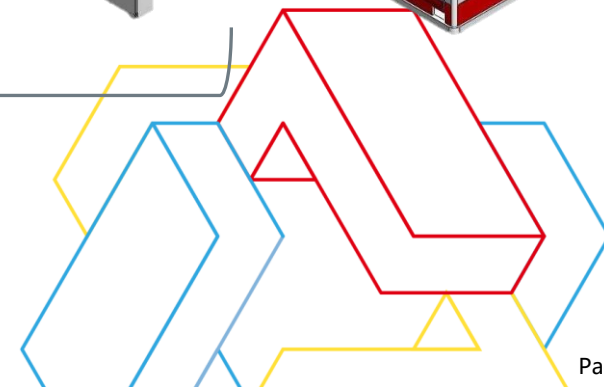


Why do we need ?



Distributed IO slave station

200m



3. Human machine interface



The medium for interaction and information exchange between systems and users





MADE WITH



4. Industrial control software

Siemens



Totally Integrated
Automation Portal



Mitsubishi



GX Works



GX Developer



Omron



CX-Programmer



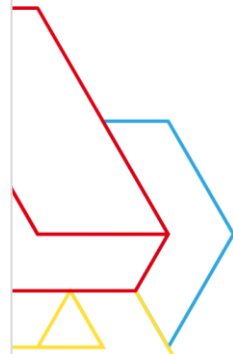
XINJE
信捷

INOVANCE
汇川技术

DELTA 台达

Allen-Bradley

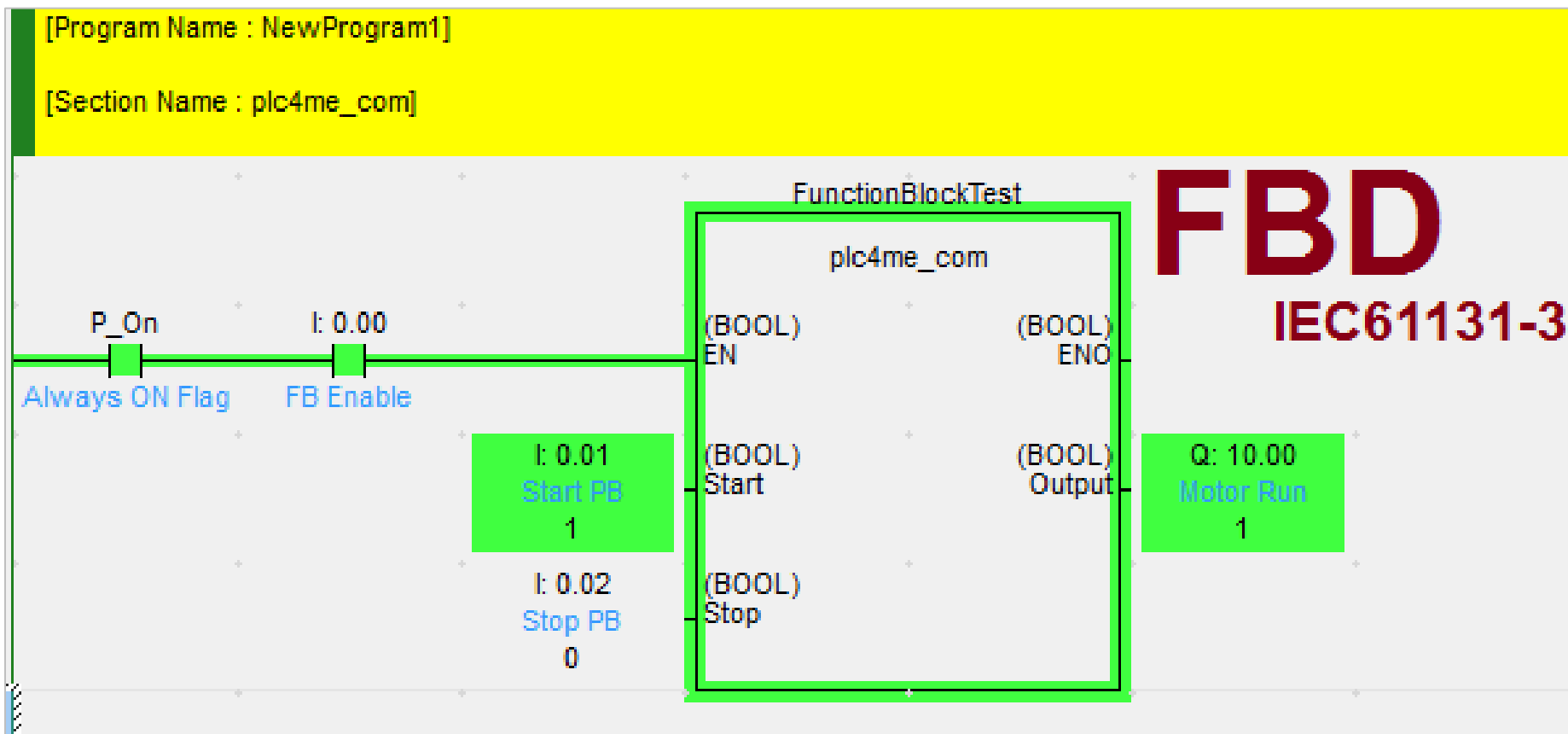
Schneider
Electric



4.1 Programming Languages

- **Function Block Diagram (The abbreviation is FBD)**

Describe the connection of functions, function blocks, and programs as a set of connected graphic blocks. It looks like the electronic circuit diagram we often use.



How to Choose a Controller



How to Choose a Controller

Security projects
require security
level certification



Safety(F)
CPU

High reliability,
reducing production
downtime



redundance(R/H)
CPU

Complex motion
control
requirements



Motion control(T)
CPU

Simple project
with limited cost



Compact(C) CPU

How to Choose a Controller

Step 1:

Consideration	Information to Record	
1. Proposed System	_____ New system	_____ Existing system

Determine whether your system is new or existing:

- Will your system be installed from scratch or are there existing products already installed?
- The rest of your system will need to be compatible with new components.



How to Choose a Controller

Step 2:

Consideration	Information to Record	
2. Environmental Issues	Codes/environmental issues to consider	No codes or environmental issues to consider

Consider any environmental issues that will affect your application (temperature, dust, vibration, codes specific to your facility, etc.).



How to Choose a Controller

Step 3:

Consideration	Information to Record	
3. Discrete Devices	_____ Total inputs: _____ AC _____ DC	_____ Total outputs: _____ AC _____ DC

Determine

- how many discrete devices your system will have.
- Which types (AC, DC, etc.) are needed?



How to Choose a Controller

Step 4:

Consideration	Information to Record	
4. Analog Devices	_____ Total inputs: _____ Voltage _____ Current _____ Thermo _____ RTD	_____ Total outputs: _____ Voltage _____ Current

Determine

- how many analog devices your system will have.
- Which types (voltage, current, temperature, etc.) are needed?



How to Choose a Controller

Step 5:

Consideration	Information to Record
5. Specialty Modules or Features (application-specific)	High speed counter Positioning Servo/stepper BASIC programming Real-time clock Others (list)

Determine whether your system will require any specialty features:

- Will your application require high-speed counting or positioning?
- What about a real-time clock or other specialty feature?



Step 6:

Consideration	Information to Record
6. <i>CPU Required</i>	Hardware requirements:
	_____ K program memory required (estimated)
	_____ K data memory required (estimated)
	_____ Fast scan time required?
	_____ Battery backup required?
	Software/special function requirements:
	_____ PID
	_____ Floating Point Math
	Others (see Programming section below)

Determine the type of CPU you will need:

- How much memory will your system require?
- How many devices will your system have (determines data memory)?
- How large is your program, and what types of instructions will your program include (determines program memory)?
- How fast a scan time do you need?



How to Choose a Controller

Step 7:

Consideration	Information to Record	
7. I/O Locations	Local ... only	Remote Locations Specific remote I/O protocol required? Which one?

Determine where your I/O will be located:
Will your system require only local I/O, or both local and remote I/O locations?



How to Choose a Controller

Step 8:

Consideration	Information to Record
8. Communications	☐ Ethernet
	☐ PLC to PLC
	☐ Modbus RTU
	☐ ASCII (interface to serial devices)
	☐ Other

Enter number of physical locations needed, and if/what specific protocol may be required. Determine your communication requirements:
Will your system be communicating to other networks, systems or field devices?



How to Choose a Controller

Step 9:

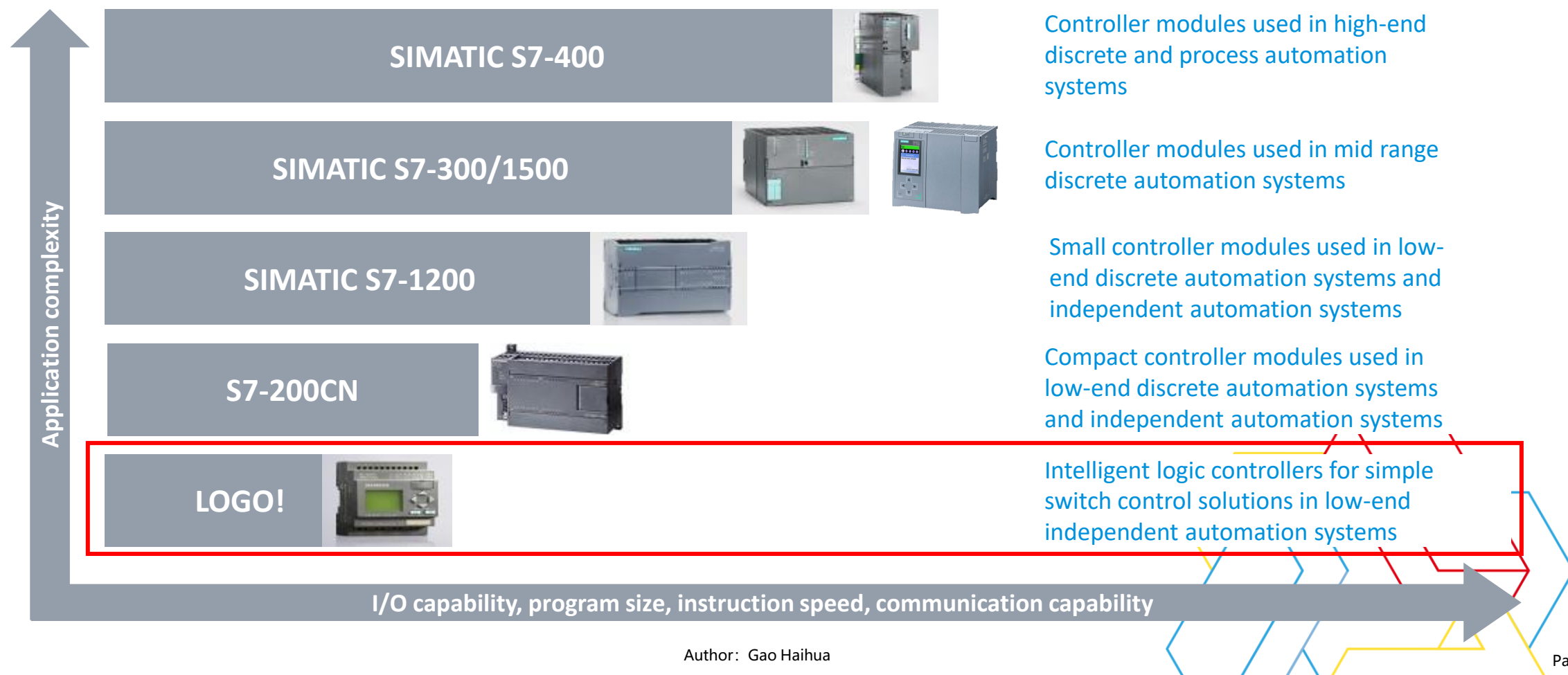
Consideration	Information to Record	
9. Programming		☐ PID loops
	☐ Floating point math	☐ number of loops needed
		☐ Subroutines
	☐ Drum sequencer	☐ Direct interrupts
		☐ Others (list)

Determine your programming requirements:

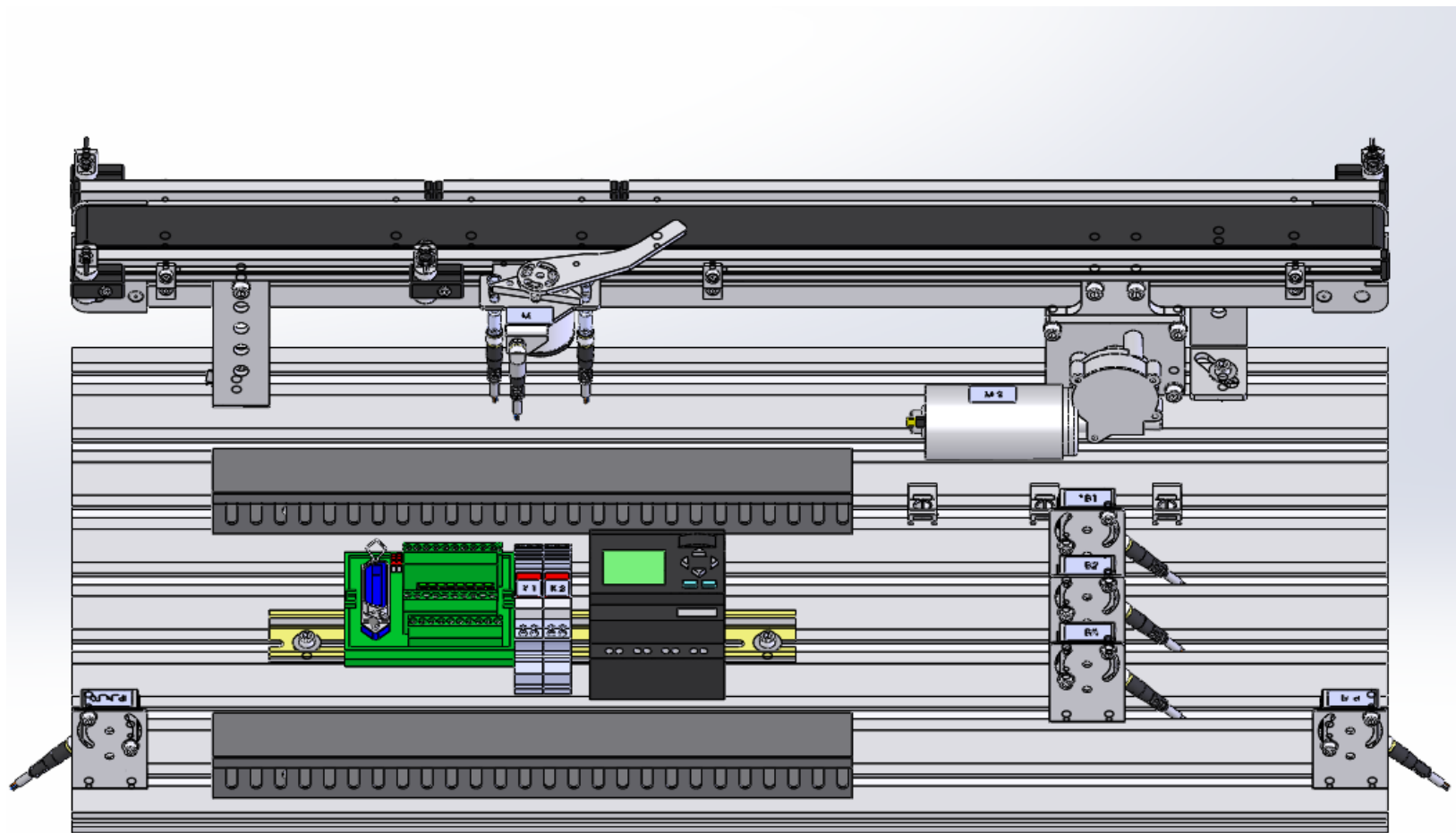
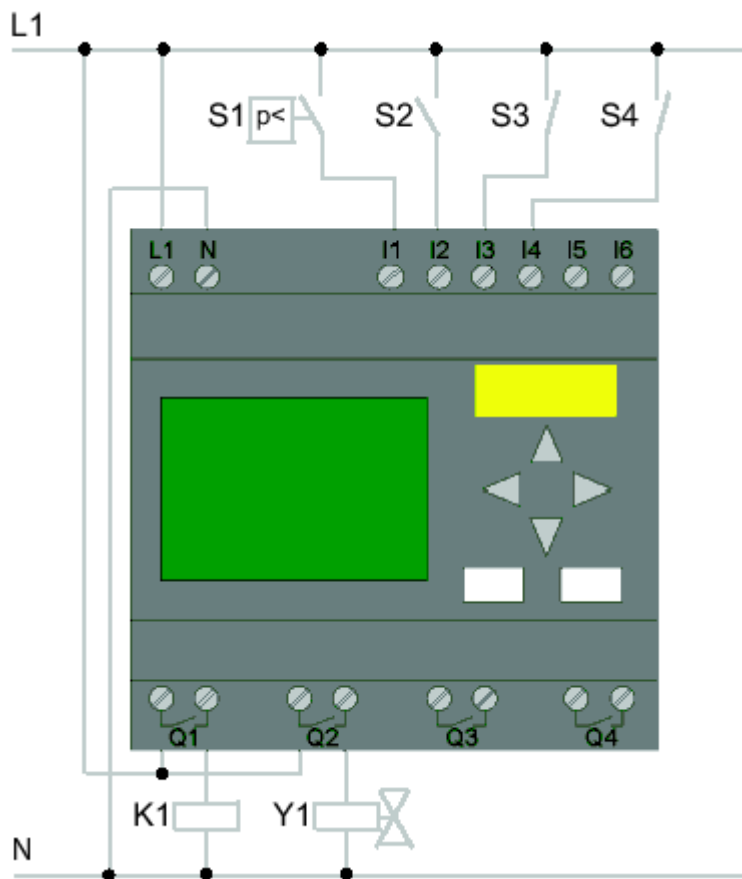
Does your application require only traditional programming instructions, or are special instructions necessary?



Siemens controller product positioning



LOGO Application



LOGO!Soft Comfort

The screenshot displays the LOGO!Soft Comfort software interface. The window title is "LOGO!Soft Comfort". The menu bar includes File, Edit, Format, View, Tools, Window, and Help. The toolbar contains various icons for file operations, editing, and execution. The left sidebar shows a tree view of components:

- Constants**
 - Digital**
 - I Input
 - C Cursor key
 - F LOGO! TD Function key
 - S Shift register bit
 - lo Status 0 (low)
 - hi Status 1 (high)
 - Q Output
 - X Open connector
 - M Flag
 - Analog**
 - AI Analog input
 - AQ Analog output
 - AM Analog flag
 - Basic functions**
 - AND
 - AND (Edge)
 - NAND
 - NAND (Edge)
 - OR
 - NOR
 - XOR
 - NOT

The main workspace, titled "Drawing1", shows a ladder logic diagram on a grid. It consists of two rungs. The first rung contains a normally open contact labeled "I1". The second rung contains a coil labeled "Q1". A vertical line connects the output of the first rung to the input of the second rung. The status bar at the bottom shows "Selection" on the left and "Modem disconnected", "OBA6. Standard", "100%", and "age 46" on the right.

Thank You !

